

## Vector fields

### Definition:

(i)  $\underline{F}$  is called a **two dimensional vector field** if  $\underline{F}$  is a two dimensional vector valued function of two variables. There exists two scalar valued functions (say,  $P$  and  $Q$ ) of two variables, called **component functions of  $\underline{F}$**  such that  $\underline{F} = P\underline{i} + Q\underline{j}$ .

(ii)  $\underline{F}$  is called a **three dimensional vector field** if  $\underline{F}$  is a three dimensional vector valued function of three variables. There exists three scalar valued functions (say,  $P$ ,  $Q$  and  $R$ ) of three variables, called **component functions of  $\underline{F}$**  such that  $\underline{F} = P\underline{i} + Q\underline{j} + R\underline{k}$ .

**Example:** If  $f$  is a scalar valued function of two or three variables, then  $\nabla f$  is a two or three dimensional vector field respectively.

**Definition:** A vector field  $\underline{F}$  is called **conservative** if there exists a scalar valued function  $f$  such that  $\underline{F} = \nabla f$ . In such a case,  $f$  is called the **potential function** of  $\underline{F}$ .

**Theorem 1 (Mixed derivative theorem for two dimensional conservative vector fields):** If  $\underline{F}(x, y) = P(x, y)\underline{i} + Q(x, y)\underline{j}$  is a **conservative vector field** such that  $P$  and  $Q$  have continuous first-order partial derivative for  $(x, y)$  in  $D$ , then

$$\frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x} \quad \text{in } D.$$

**Theorem 2 (Converse of Theorem 1):** If  $\underline{F}(x, y) = P(x, y)\underline{i} + Q(x, y)\underline{j}$  is a vector field for  $(x, y)$  in an **open, simply connected region**  $D$  such that  $P$  and  $Q$  have continuous first-order partial derivative and  $\frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x}$  in  $D$ , then  $\underline{F}$  is a conservative vector field in  $D$ , that is, there exist a scalar valued function  $f$  defined over  $D$  such that  $\underline{F} = \nabla f$ .

## Line integrals over an oriented curve

Let  $C$  be an oriented curve with a starting and an ending point lying in two or three dimensional space.

### (I) Line integrals of a scalar valued function

**Definition:** If  $f$  is a scalar valued function of two or three variables, then the **line integral of  $f$  over  $C$  with respect to arc length**, denoted by  $\int_C f(x, y) ds$  or  $\int_C f(x, y, z) ds$ , is given by

$$\int_C f(x, y) ds = \lim_{n \rightarrow \infty} \sum_{i=1}^n f(x_i^*, y_i^*) \Delta s_i \quad \text{or} \quad \int_C f(x, y, z) ds = \lim_{n \rightarrow \infty} \sum_{i=1}^n f(x_i^*, y_i^*, z_i^*) \Delta s_i$$

if the limit exists where  $s$  denotes the arc length on  $C$ . Similarly, one can also define the **line integral of  $f$  over  $C$  with respect to the given variables**, namely,

$$\int_C f(x, y) dx \quad \& \quad \int_C f(x, y) dy \quad \text{or} \quad \int_C f(x, y, z) dx, \int_C f(x, y, z) dy \quad \& \quad \int_C f(x, y, z) dz.$$

### (II) Line integrals of a vector field

**Definition:** If  $\underline{F}$  is a two or three dimensional vector field, then the **line integral of  $\underline{F}$  over  $C$** , denoted by  $\int_C \underline{F} \cdot \underline{T} ds$ , is given by

$$\int_C \underline{F} \cdot \underline{T} ds = \lim_{n \rightarrow \infty} \sum_{i=1}^n [\underline{F}(x_i^*, y_i^*) \cdot \underline{T}|_{(x_i^*, y_i^*)}] \Delta s_i \quad \text{or} \quad \int_C \underline{F} \cdot \underline{T} ds = \lim_{n \rightarrow \infty} \sum_{i=1}^n [\underline{F}(x_i^*, y_i^*, z_i^*) \cdot \underline{T}|_{(x_i^*, y_i^*, z_i^*)}] \Delta s_i$$

if the limit exists where  $\underline{T}$  denotes unit tangent vector on  $C$ .

#### **Formula:**

(a) **Two dimensional case:** If the oriented curve  $C$  is given by  $\underline{r}(t) = \langle x(t), y(t) \rangle$  for  $a \leq t \leq b$ ,  $f$  is a scalar valued function of two variables,  $\underline{F} = \langle P, Q \rangle$  is a two dimensional vector field, then

$$\begin{aligned} \int_C f(x, y) ds &= \int_a^b f(\underline{r}(t)) |\underline{r}'(t)| dt = \int_a^b f(x(t), y(t)) \sqrt{(x'(t))^2 + (y'(t))^2} dt \\ \int_C f(x, y) dx &= \int_a^b f(\underline{r}(t)) x'(t) dt = \int_a^b f(x(t), y(t)) x'(t) dt \\ \int_C f(x, y) dy &= \int_a^b f(\underline{r}(t)) y'(t) dt = \int_a^b f(x(t), y(t)) y'(t) dt \\ \int_C \underline{F} \cdot \underline{T} ds &= \int_a^b [\underline{F}(\underline{r}(t)) \cdot \underline{r}'(t)] dt = \int_a^b [P(x(t), y(t)) x'(t) + Q(x(t), y(t)) y'(t)] dt \end{aligned}$$

(b) **Three dimensional case:** If the oriented curve  $C$  is given by  $\underline{r}(t) = \langle x(t), y(t), z(t) \rangle$  for  $a \leq t \leq b$ ,  $f$  is a scalar valued function of three variables,  $\underline{F} = \langle P, Q, R \rangle$  is a three dimensional vector field, then

$$\int_C f(x, y, z) ds = \int_a^b f(\underline{r}(t)) |\underline{r}'(t)| dt = \int_a^b f(x(t), y(t), z(t)) \sqrt{(x'(t))^2 + (y'(t))^2 + (z'(t))^2} dt$$

$$\int_C f(x, y, z) dx = \int_a^b f(\underline{r}(t)) x'(t) dt = \int_a^b f(x(t), y(t), z(t)) x'(t) dt$$

$$\int_C f(x, y, z) dy = \int_a^b f(\underline{r}(t)) y'(t) dt = \int_a^b f(x(t), y(t), z(t)) y'(t) dt$$

$$\int_C f(x, y, z) dz = \int_a^b f(\underline{r}(t)) z'(t) dt = \int_a^b f(x(t), y(t), z(t)) z'(t) dt$$

$$\int_C \underline{F} \cdot \underline{T} ds = \int_a^b [\underline{F}(\underline{r}(t)) \cdot \underline{r}'(t)] dt = \int_a^b [P(x(t), y(t), z(t)) x'(t) + Q(x(t), y(t), z(t)) y'(t) + R(x(t), y(t), z(t)) z'(t)] dt$$

**Other Notations:** Sometimes  $\int_C \underline{F} \cdot \underline{T} ds$  is denoted by  $\int_C \underline{F} \cdot d\underline{r}$  and also by  $\int_C P dx + Q dy$  or

$$\int_C P dx + Q dy + R dz.$$

**Remark:** The right hand sides in the formulas do not depend on the choice of the representative  $\underline{r}$  for the oriented curve  $C$ .

### **Properties of line integrals:**

(i) If  $-C$  denote the same curve  $C$  but with reverse orientation, then  $\int_{-C} f ds = -\int_C f ds$  and

$$\int_{-C} \underline{F} \cdot \underline{T} ds = -\int_C \underline{F} \cdot \underline{T} ds.$$

(ii) If  $C_1$  and  $C_2$  be two oriented curves such that  $C_1$  finishes at the point where  $C_2$  starts, then

$$\int_{C_1 \cdot C_2} = \int_{C_1} + \int_{C_2} \quad \text{where } C_1 \cdot C_2 \text{ is the curve obtained by joining } C_1 \text{ and } C_2.$$

(iii)  $\int_C ds = \text{length of the curve } C$ .

**Fundamental theorem of line integrals:** If  $C$  is a smooth oriented curve starting at the point  $A$  & ending at the point  $B$ , and  $f$  is a scalar valued function of two or three variables such that  $\nabla f$  is continuous at all points on  $C$ , then

$$\int_C \nabla f \cdot \underline{T} ds = f|_B - f|_A$$